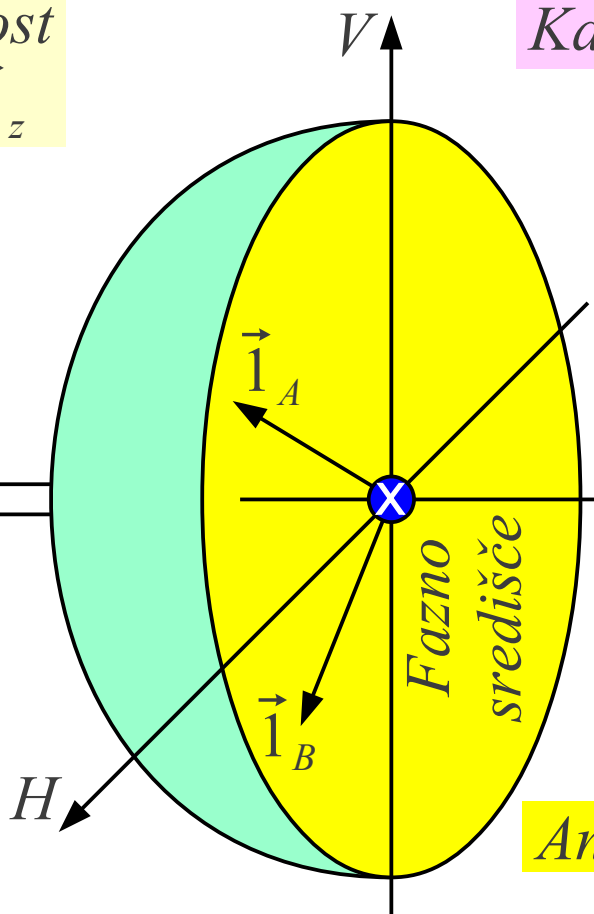


Polarizacija

Desnosučnost
 $\vec{1}_V \times \vec{1}_H = \vec{1}_z$

Kartezične koordinate (V, H, z)

Generator
 $I_g = |I_g| e^{j\phi_g}$



$$\vec{E} = \vec{\alpha} I_g \frac{e^{-jkr}}{r} = \vec{1}_V E_V + \vec{1}_H E_H$$

Razširjanje $\frac{e^{-jkr}}{r}$

Smer glavnega snopa sevanja

Razmerje premikih komponent

$$\frac{E_V}{E_H} = \frac{\vec{\alpha} \cdot \vec{1}_V}{\vec{\alpha} \cdot \vec{1}_H} = \frac{\alpha_V}{\alpha_H}$$

Premo – polarizirani komponenti

$$E_V = \vec{E} \cdot \vec{1}_V = \vec{\alpha} \cdot \vec{1}_V |I_g| e^{j\phi_g} \frac{e^{-jkr}}{r}$$

$$E_H = \vec{E} \cdot \vec{1}_H = \vec{\alpha} \cdot \vec{1}_H |I_g| e^{j\phi_g} \frac{e^{-jkr}}{r}$$

Poševna prema smernika

$$\vec{1}_A = \vec{1}_{(45^\circ)} = \frac{\vec{1}_V + \vec{1}_H}{\sqrt{2}}$$

$$\vec{1}_B = \vec{1}_{(135^\circ)} = \frac{\vec{1}_H - \vec{1}_V}{\sqrt{2}}$$

Koordinatni sistem za polarizacijo antene

Krožna smernika

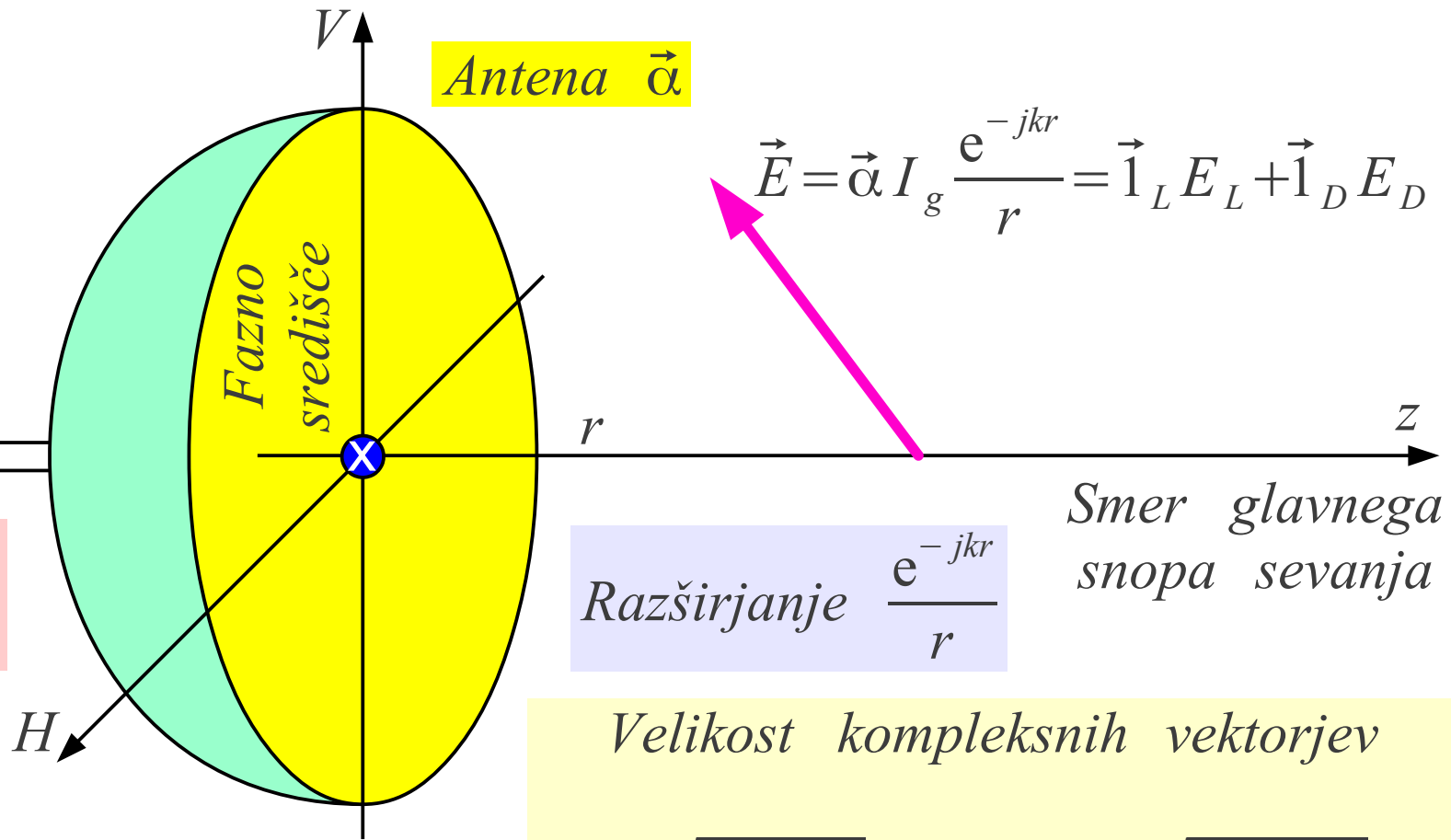
$$\vec{1}_L = \frac{\vec{1}_V + j\vec{1}_H}{\sqrt{2}}$$

$$\vec{1}_D = \frac{\vec{1}_V - j\vec{1}_H}{\sqrt{2}}$$



Generator

$$I_g = |I_g| e^{j\phi_g}$$



Antena $\vec{\alpha}$

$$\vec{E} = \vec{\alpha} I_g \frac{e^{-jkr}}{r} = \vec{1}_L E_L + \vec{1}_D E_D$$

Smer glavnega snopa sevanja

Razširjanje $\frac{e^{-jkr}}{r}$

Velikost kompleksnih vektorjev

$$|\vec{1}_L| = \sqrt{\vec{1}_L \cdot \vec{1}_L^*} = 1 \quad |\vec{1}_D| = \sqrt{\vec{1}_D \cdot \vec{1}_D^*} = 1$$

Pravokotnost $\vec{1}_D \cdot \vec{1}_L^* = \vec{1}_L \cdot \vec{1}_D^* = 0$

Krožno – polarizirane komponente

$$E_L = \vec{E} \cdot \vec{1}_L^* = \vec{\alpha} \cdot \vec{1}_L^* |I_g| e^{j\phi_g} \frac{e^{-jkr}}{r}$$

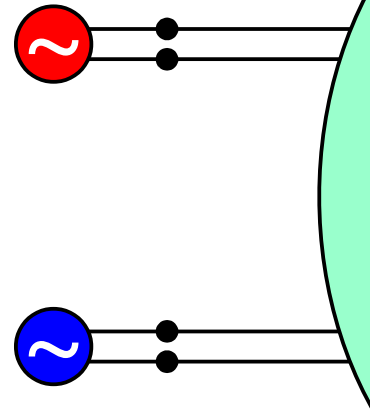
$$E_D = \vec{E} \cdot \vec{1}_D^* = \vec{\alpha} \cdot \vec{1}_D^* |I_g| e^{j\phi_g} \frac{e^{-jkr}}{r}$$

Razmerje krožnih komponent

$$Q = \frac{E_L}{E_D} = \frac{\vec{\alpha} \cdot \vec{1}_L^*}{\vec{\alpha} \cdot \vec{1}_D^*}$$

Krožni smerniki in komponente

Generator #1
 $I_1 = |I_1| e^{j\phi_1}$



Generator #2
 $I_2 = |I_2| e^{j\phi_2}$

Dvopolarizacijska
 antenna

$$\vec{E}_1 = \vec{1}_{E_1} E_1 = \frac{\vec{1}_L Q_1 + \vec{1}_D}{\sqrt{|Q_1|^2 + 1}} E_1$$

$$\vec{E}_2 = \vec{1}_{E_2} E_2 = \frac{\vec{1}_L Q_2 + \vec{1}_D}{\sqrt{|Q_2|^2 + 1}} E_2$$

Pravokotnost $\vec{E}_1 \perp \vec{E}_2 \rightarrow \vec{E}_1 \cdot \vec{E}_2^* = 0$

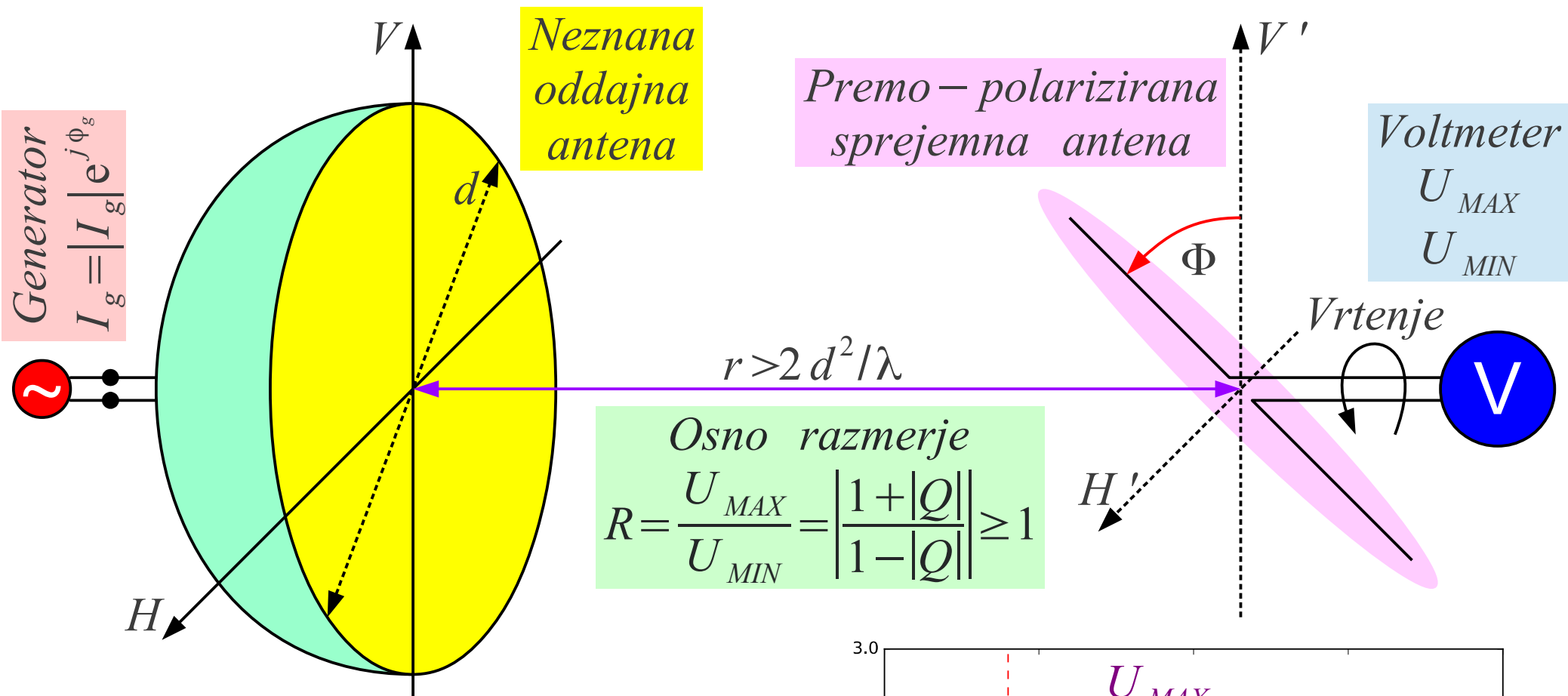
$$(\vec{1}_L Q_1 + \vec{1}_D) \cdot (\vec{1}_L Q_2 + \vec{1}_D)^* = 0$$

$$Q_1 Q_2^* + 1 = 0$$

$$Q_1 = -\frac{1}{Q_2^*} \quad Q_2 = -\frac{1}{Q_1^*}$$

$Q = 0 \equiv$ desna - krožna polarizacija
 $|Q| < 1 \equiv$ desna - eliptična polarizacija
 $|Q| = 1 \equiv$ prema polarizacija
 $|Q| > 1 \equiv$ leva - eliptična polarizacija
 $Q \rightarrow \infty \equiv$ leva - krožna polarizacija

Razmerje krožnih komponent



Neznana oddajna antena

Premo – polarizirana sprejemna antena

Voltmeter
 U_{MAX}
 U_{MIN}

Osno razmerje

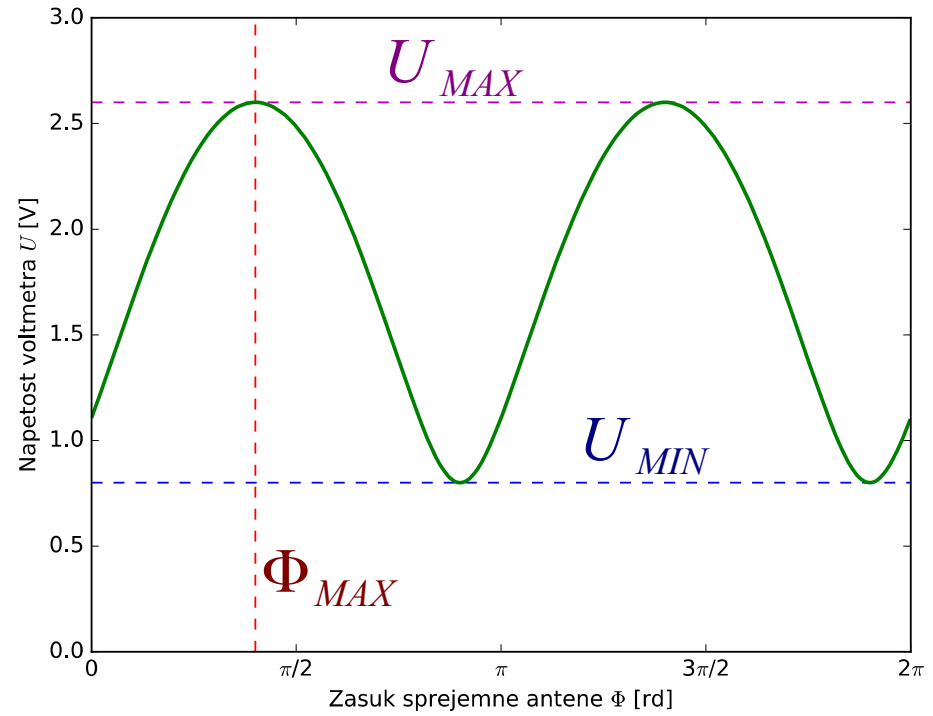
$$R = \frac{U_{MAX}}{U_{MIN}} = \left| \frac{1 + |Q|}{1 - |Q|} \right| \geq 1$$

$$R_{dB} = 20 \log_{10} R = 20 \log_{10} \frac{U_{MAX}}{U_{MIN}}$$

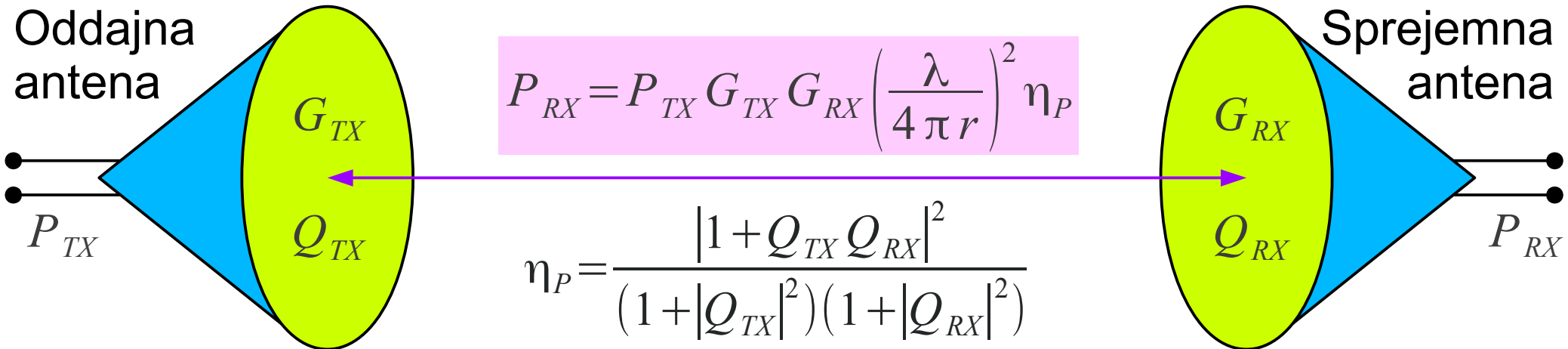
Desna $|Q| = \frac{R-1}{R+1} \leq 1$

Leva $|Q| = \frac{R+1}{R-1} \geq 1$

$$Q = |Q| e^{-j2\Phi_{MAX}}$$



Osno razmerje antene



Polarizacija TX		Q_{TX}	R_{TX}	Faktor skladnosti η_p (polarizacija RX)					
				VP	HP	RHCP	LHCP	P_{45°	P_{135°
VP	$\vec{1}_V$	1	∞	1	0	1/2	1/2	1/2	1/2
HP	$\vec{1}_H$	-1	∞	0	1	1/2	1/2	1/2	1/2
RHCP	$\vec{1}_D = (\vec{1}_V - j\vec{1}_H) / \sqrt{2}$	0	1	1/2	1/2	1	0	1/2	1/2
LHCP	$\vec{1}_L = (\vec{1}_V + j\vec{1}_H) / \sqrt{2}$	∞	1	1/2	1/2	0	1	1/2	1/2
P_{45°	$\vec{1}_A = (\vec{1}_V + \vec{1}_H) / \sqrt{2}$	-j	∞	1/2	1/2	1/2	1/2	0	1
P_{135°	$\vec{1}_B = (\vec{1}_H - \vec{1}_V) / \sqrt{2}$	j	∞	1/2	1/2	1/2	1/2	1	0

Faktor skladnosti polarizacije

George Gabriel Stokes 1852

$$s_0 = P_V + P_H = P_A + P_B = P_L + P_D$$

$$s_1 = P_V - P_H = m s_0 \frac{2 \operatorname{Re}[Q]}{|Q|^2 + 1}$$

$$s_2 = P_A - P_B = m s_0 \frac{-2 \operatorname{Im}[Q]}{|Q|^2 + 1}$$

$$s_3 = P_L - P_D = m s_0 \frac{|Q|^2 - 1}{|Q|^2 + 1}$$

Hitri opazovalec

$B_{\text{opazovalca}} \gg B_{\text{signala}}$

$$s_0 = \sqrt{s_1^2 + s_2^2 + s_3^2} \quad m = 1$$

Počasni opazovalec

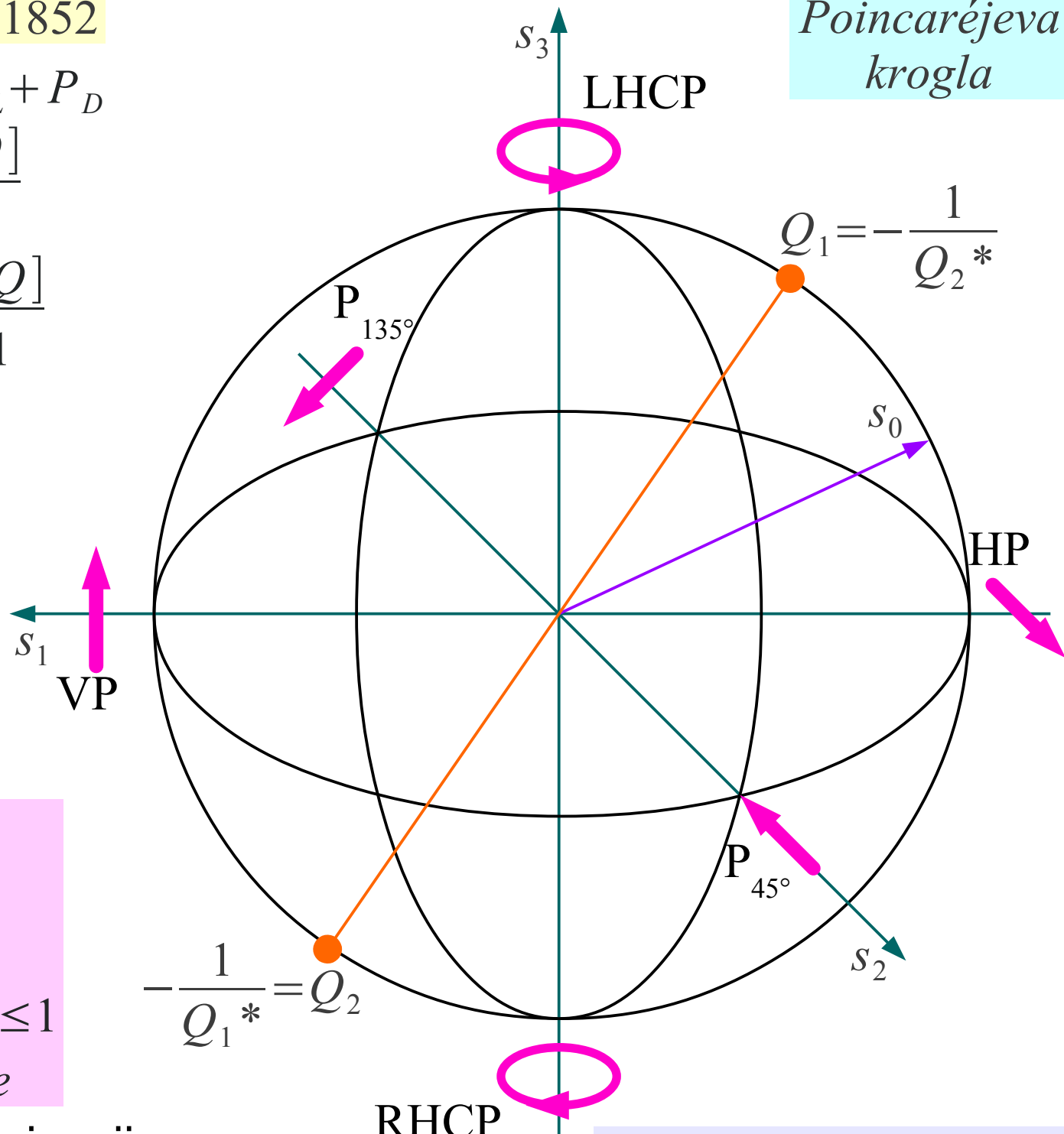
$B_{\text{opazovalca}} \ll B_{\text{signala}}$

$$m s_0 = \sqrt{s_1^2 + s_2^2 + s_3^2} \quad 0 \leq m \leq 1$$

$m \equiv$ stopnja polarizacije

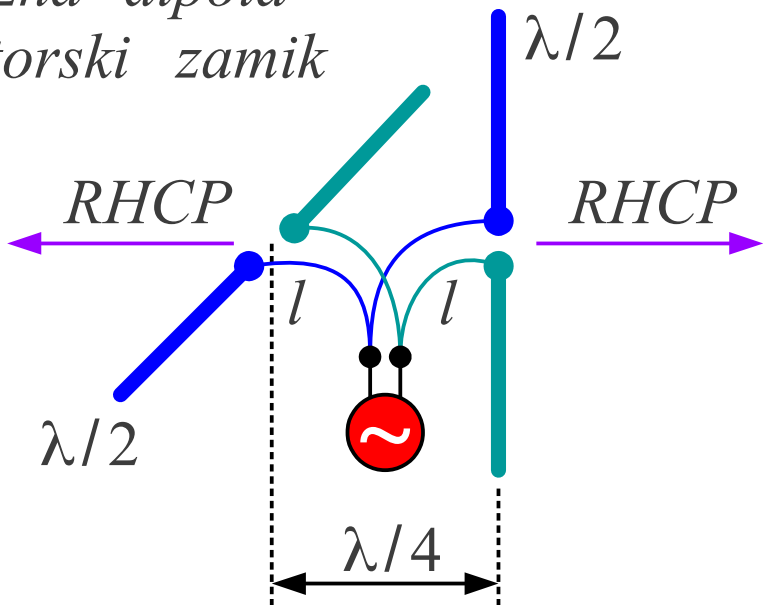
Stokesovi parametri polarizacije

Poincaréjeva krogla

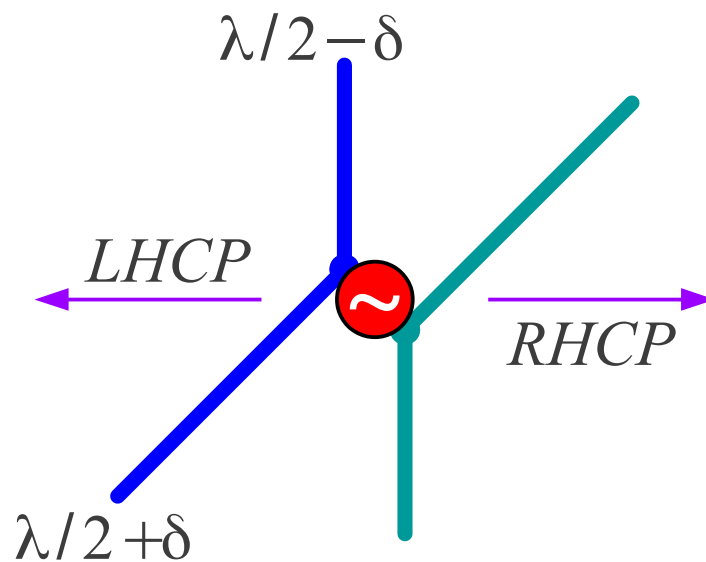


Henri Poincaré 1892

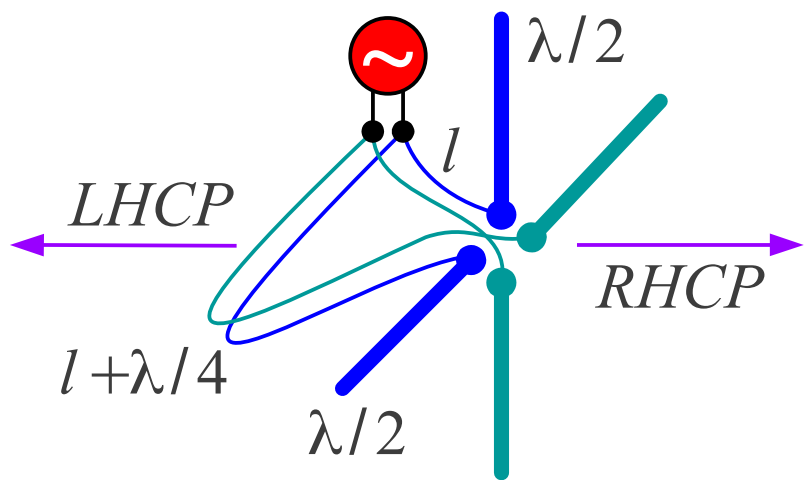
*Križna dipola
prostorski zamik*



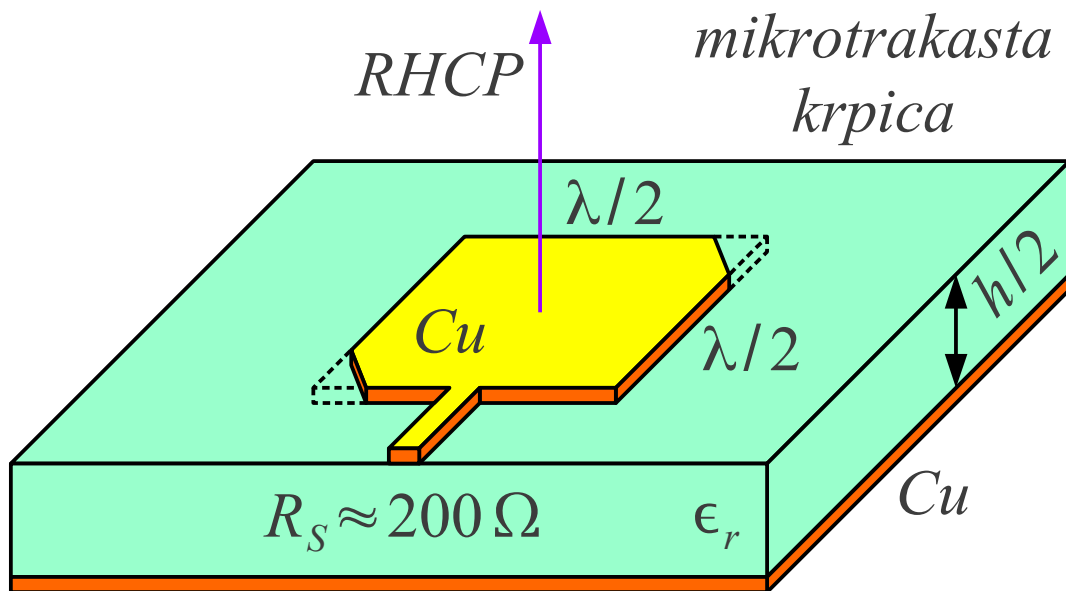
*Križna dipola
različnih dolžin*



*Križna dipola
kvadraturno napajanje*

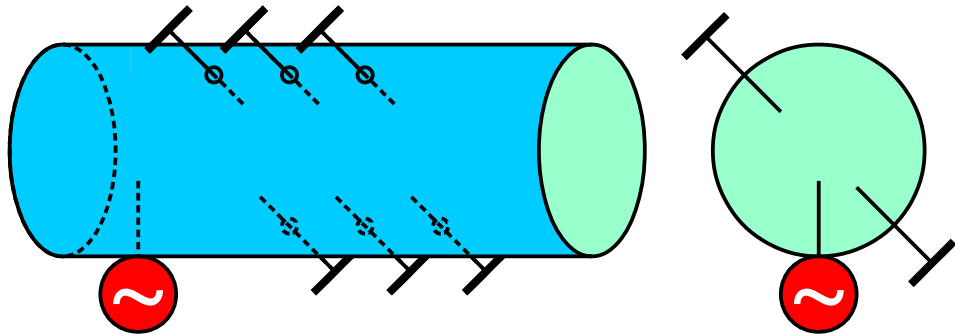


*Obrezana
mikrotrakasta
krpica*



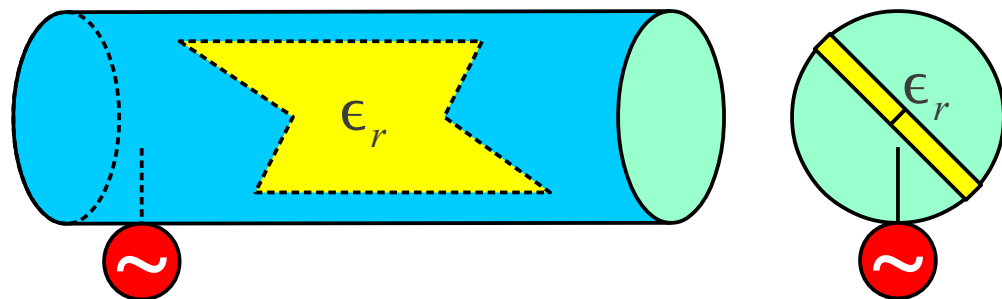
Krožno-polarizirani dipoli

Lonček RHCP



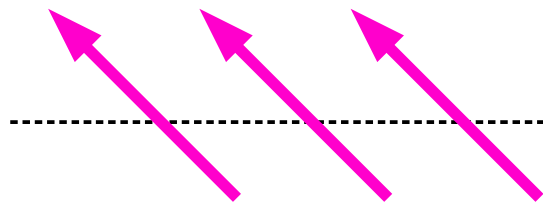
Uglaševalni vijaki pod 45°

Lonček RHCP

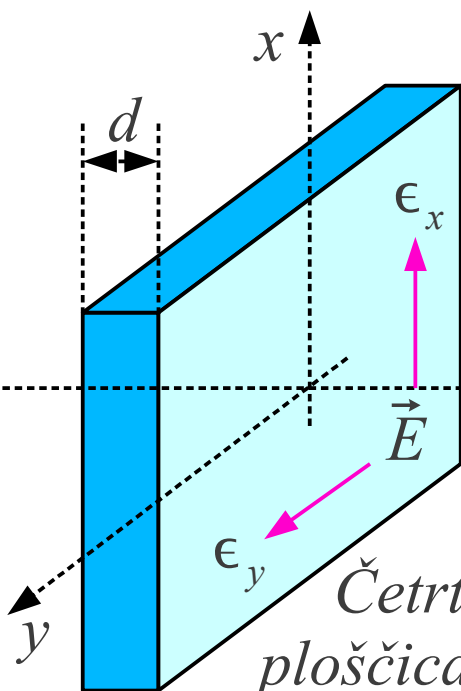


Dielektrična ploščica pod 45°

Poševna polarizacija 45°



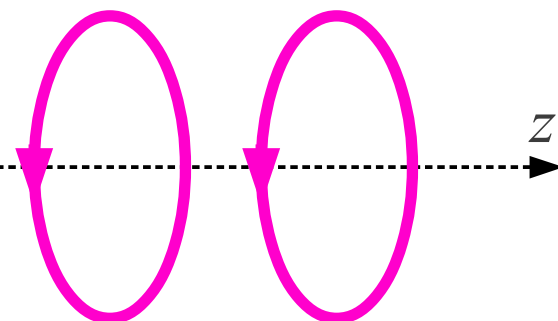
$$\Delta\phi = k_y d - k_x d = \Delta n \frac{2\pi}{\lambda} d$$



Četrťvalovna ploščica $\Delta\phi = \pi/2$

$$d = \frac{\lambda}{2\pi} \frac{\Delta\phi}{\Delta n}$$

HeNe $\lambda \approx 633\text{nm}$
 Sljuda $\Delta n \approx 0.005$
 $d \approx 32\mu\text{m}$



Desna – krožna polarizacija RHCP

Krožna polarizacija preko dvolomnosti

Arhimedova spirala $\rho = \alpha \phi$

$$dl = \rho d\phi = \alpha \phi d\phi$$

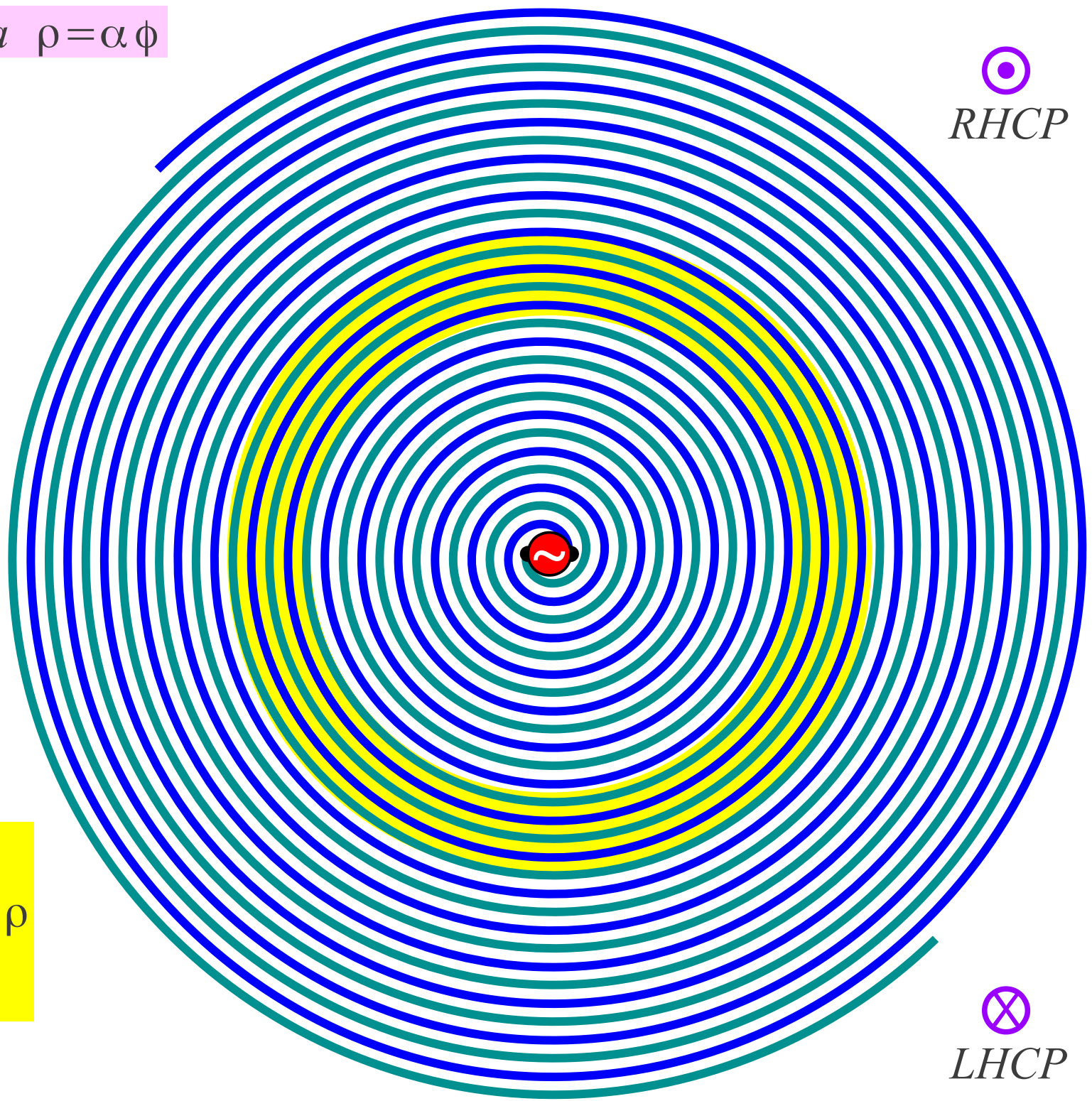
$$l_1 = \int_0^{\phi} \alpha \phi d\phi = \frac{\alpha \phi^2}{2}$$

$$l_2 = \int_{\pi}^{\phi+\pi} \alpha \phi d\phi =$$
$$= \alpha \left[\frac{(\phi+\pi)^2}{2} - \frac{\pi^2}{2} \right]$$
$$l_2 = \alpha \frac{\phi^2}{2} + \alpha \pi \phi$$

Aktivni kolobar

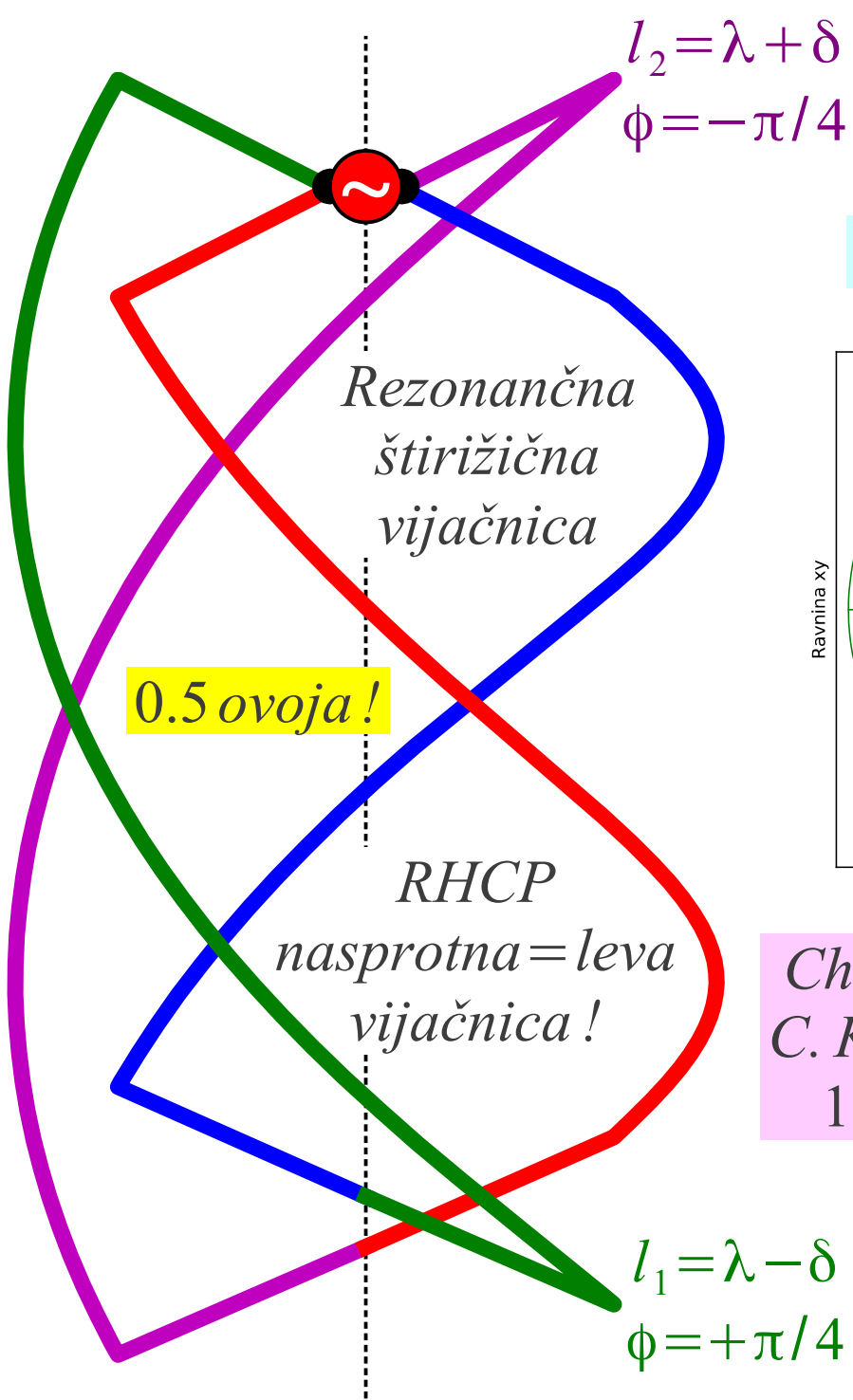
$$\frac{\lambda}{2} \approx l_2 - l_1 = \alpha \pi \phi = \pi \rho$$
$$\lambda \approx 2 \pi \rho$$

Dvokraka spirala

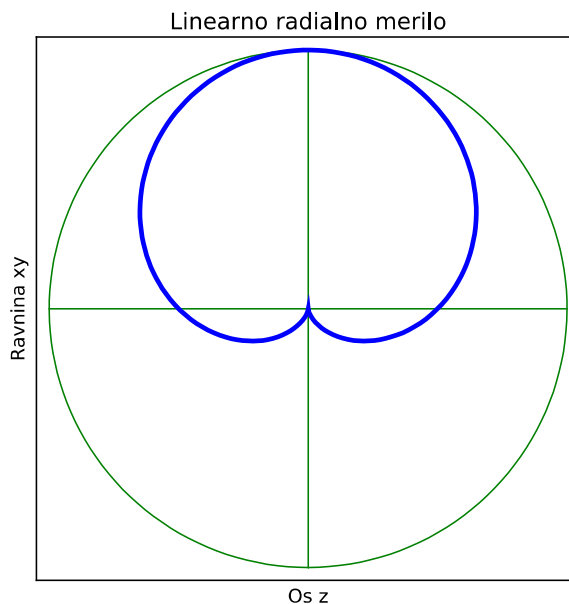



RHCP


LHCP



$$F(\Theta, \Phi) \approx 1 + \cos \Theta$$

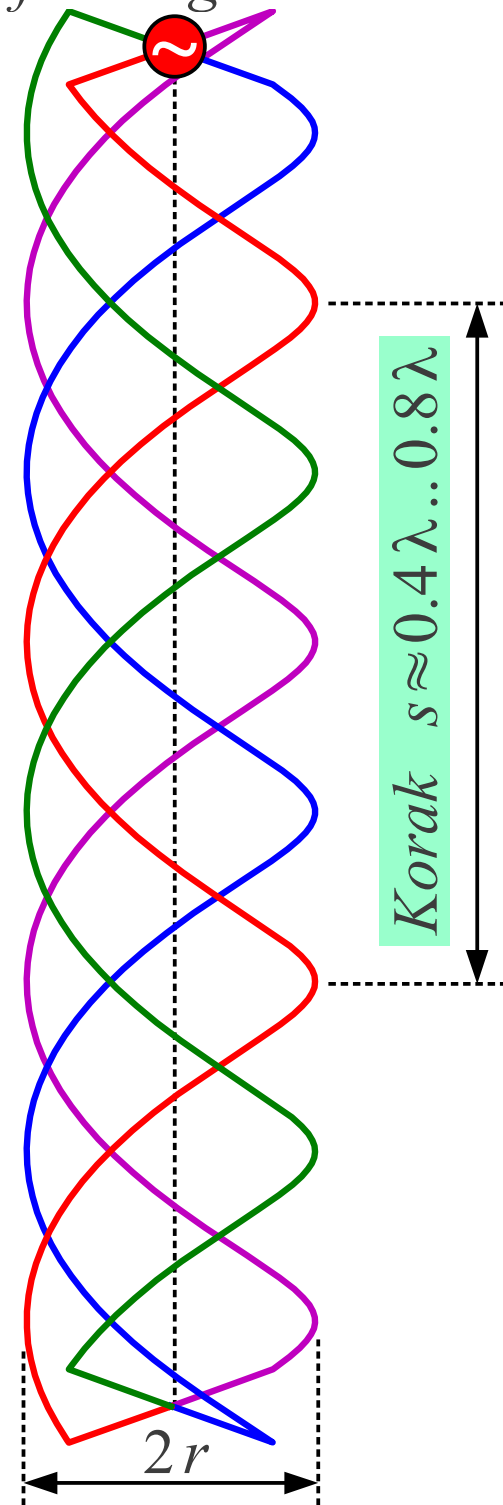


Charles
C. Kilgus
1968

RHCP
štirižična
vijačnica
2 ovoja

Polmer vijačnice
 $r \approx 0.02 \lambda .. 0.12 \lambda$

Štirifazni generator



Štirižična vijačna antena z vzratnim sevanjem