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DATA LINK PROCESSOR ON PC

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DATA LINK PROCESSOR ON PC

by

Patrick HUNT

Summary

A Mode-S Data Link Processor developed on a PC using PASCAL and a Real Time Operating System.

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1. GENERAL

Earlier this year, it was required to build a DLP (Data Link Processor) for a differential GPS/Mode-S application (See Technical Note No. 01/95 by P. HUNT/L. CROUZARD).

For this application, a Real Time Operating System based on and for PASCAL applications was purchased.

It soon became apparent that this system offered many possibilities for Mode-S application development that had been previously difficult to implement using a PC with MS-DOS due to the lack of a multitasking real time environment.

As the processing logic and interfaces have been developed for this application, it is quite simple to modify the application software for other experiments.

This note describes a DLP developed for monitoring and testing Mode-S protocols with the THOMSON radar at Orly.

2. HARDWARE DESCRIPTION

The following hardware is required for the DLP :

- a) A PC, preferably 486, with at least 1 I/O slot. A ruggedised PC is recommended for airborne applications
- b) An ARINC 718 interface card (EUROCONTROL M254 - EEC note No. 17/94). Shares dual ported memory with the PC.

See **Figure No. 1**.

3. SOFTWARE REQUIREMENTS

The real time system running on the PC is from ON-TIME GmbH, Hamburg, called ,Real Time Kernel 4.0 which exists in two versions C++ or PASCAL. The PASCAL version was used for this application which also written in PASCAL.

On the ARINC card, an assembler program written in INTEL 86 language controls the Transponder/DLP interface over the ARINC 718 lines. This interface may be a single channel or dual channel version depending on the type of transponder used.

This programme is downloaded via the PC and can be considered as a front end processor which takes the load off the PC as far as the ARINC 718 processing is concerned.

3.1. Software Description

A detailed software description is not given here. The source programme in well commented PASCAL is available on request.

See **Figure No. 2.**

4. TRANSPONDER / DLPU Messages

Uplink messages from the transponder are transferred to the PC via interrupt from the front end processor.

Downlink messages to the transponder are sent with a polling method to the front end processor.

These messages are available in the dual ported memory of the PC.

5. UPLINK PROCESSING

Uplink messages are displayed on the PC screen in real time. These messages are decoded into clear Mode-S text with all Mode-S fields displayed. DLP coded data may optionally be displayed via the control screen commands. Both 6 bit coded messages and phrase coded messages are displayed (NLR DLPU C2 coding).

The following uplink messages are displayed and the total message counts for each type of messages are also displayed in a separate window.

Close-out Messages	Comm-B & Comm-D
Surveillance Messages	UF4, UF5
Comm-A Messages	UF20, UF21, Single, Linked & Broadcast
Comm-C Messages	UF24, Two to sixteen segments

6. DOWNLINK PROCESSING

The DLP can send all types of downlink messages using the application's control window.

These are :

Cancel Messages,	Comm-B / Comm-D
Comm-B Messages	Single, linked or broadcast
Comm-D Messages	Two to sixteen segments

The messages sent downlink are displayed in the Downlink window in clear text and the downlink message counts for each type of message are displayed.

The DLP also sends downlink GICB messages to the transponder. This is a standard set of parameters of which the GMT parameter is dynamic and taken from the PC's timer.

GICB messages may be inhibited from the control window.

7. CONTROL WINDOW

With the control window, on-line real time commands may be sent to the application.

This window is menu driven and self evident in use .

One can control the following processes :

- a) Send downlink messages,
- b) Enable/Disable GICB messages,
- c) Enable/Disable on-line time dated recording on hard disk,
- d) Enable/Disable DLPU C2 message decoding,
- e) Reset message counts,
- f) Stop application.

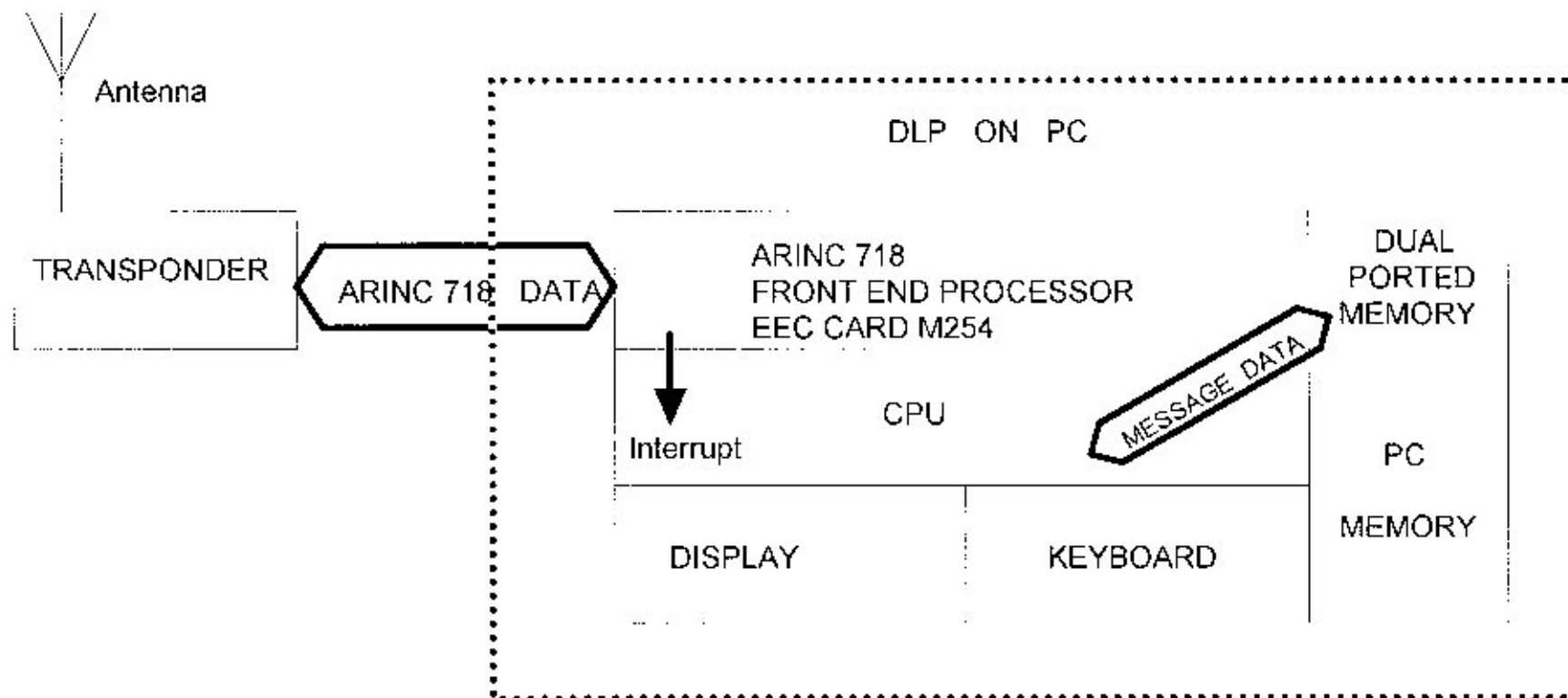
The PC time and CPU % occupation are also displayed on the screen.

See **Figures Nos. 3 & 4** for examples of the PC screen and **Figures Nos. 5 & 6** for examples of on-line recording

8. CONCLUSION

The Data Link Processor on PC has proved to be a very useful tool when investigating Mode-S protocol problems with the Orly radar or when monitoring or recording transponder/DLP activity.

The executable application programme is available for free distribution. A licence must however be obtained from ON-TIME GmbH if further development or modification is to be made to the application.



HARDWARE SCHEMATIC

Figure No. 1

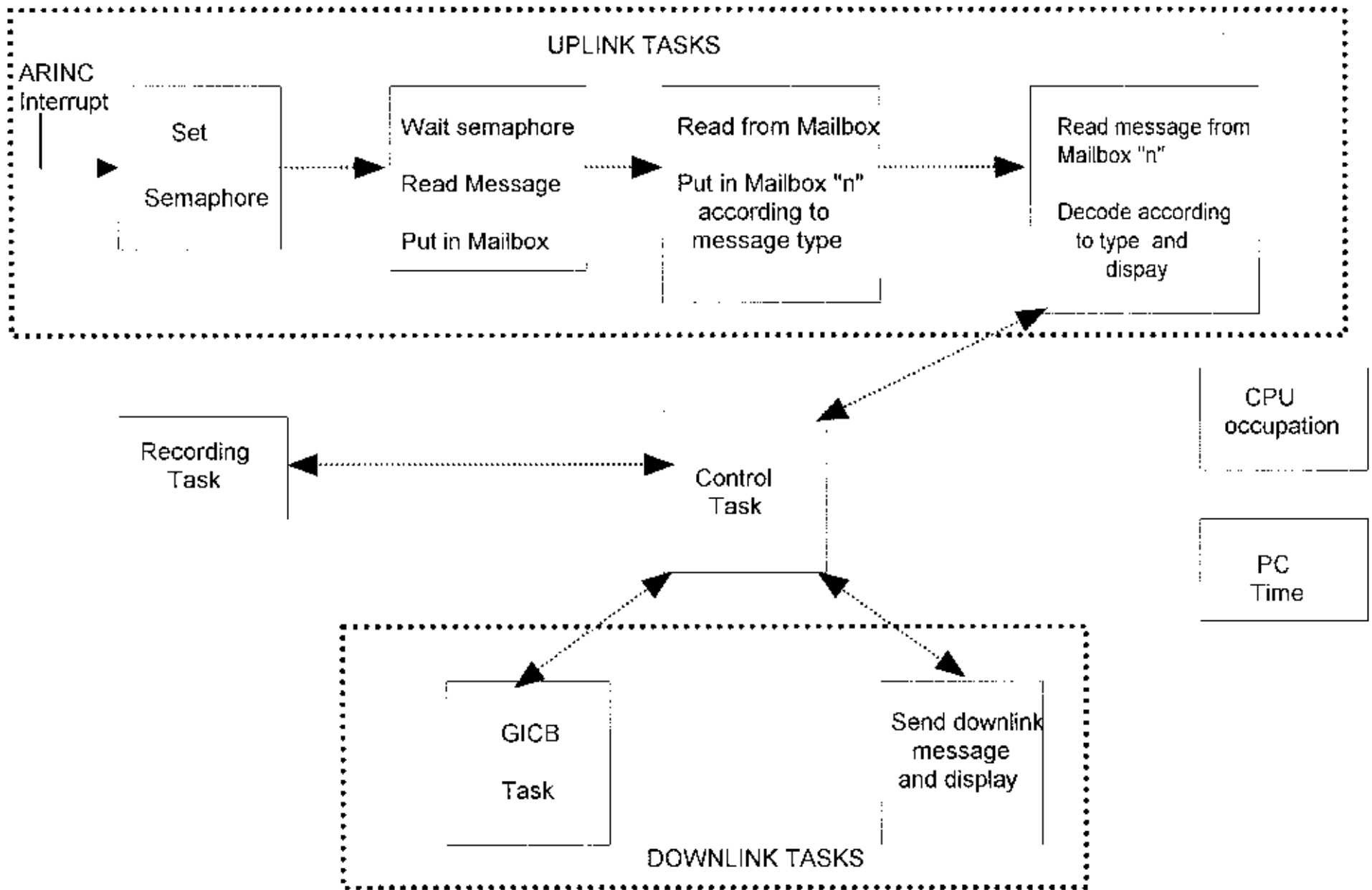


Figure No. 2

SOFTWARE SCHEMATIC SHOWING MAIN TASKS

Path: C:\TP\DLP

File: EX1.DAT 2,012 .a..27-10-94 15:04:42

Page 1

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9:45:26 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:26 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:26 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:26 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:26 uf4 pc=0 rr=22 di=7 iis=5 rrs=1 los=1 tms=0
9:45:35 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:35 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:35 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:35 uf4 pc=0 rr=22 di=7 iis=5 rrs=1 los=1 tms=0
9:45:35 uf4 pc=0 rr=27 di=0 iis=5
9:45:36 rcn=1 3 seg AICB
CBL 2ND-SEGT 3RD-SEG
9:45:44 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:44 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:44 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:44 uf4 pc=0 rr=22 di=7 iis=5 rrs=1 los=1 tms=0
9:45:44 uf4 pc=0 rr=27 di=0 iis=5
9:45:44 uf4 pc=0 rr=21 di=7 iis=5 rrs=2 los=1 tms=0
9:45:53 uf4 pc=0 rr=16 di=1 iis=5 mbs=1 mes=0 los=1 rss=1 tms=0
9:45:53 uf4 pc=0 rr=16 di=1 iis=5 mbs=1 mes=0 los=1 rss=1 tms=0
9:45:53 uf4 pc=0 rr=16 di=1 iis=5 mbs=1 mes=0 los=1 rss=1 tms=0
9:45:53 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:53 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:45:53 uf4 pc=0 rr=22 di=7 iis=5 rrs=1 los=1 tms=0
9:45:53 uf4 pc=0 rr=27 di=1 iis=5 mbs=2 mes=0 los=1 rss=0 tms=0
9:45:53 CommB Closeout rcn=1 uii=0
9:46: 2 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:46: 2 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0
9:46: 2 uf4 pc=0 rr=23 di=7 iis=5 rrs=1 los=1 tms=0

```

Example of On-line recording File
Radar Surveillance with BDS extraction

Figure 5

@

14:23:51 uf4 pc=0 rr=28 di=1 iis=6 mbs=0 mes=0 los=1 rss=0 tms=0
14:23:51 uf4 pc=0 rr=28 di=1 iis=6 mbs=0 mes=0 los=1 rss=0 tms=0
14:23:51 uf4 pc=0 rr=26 di=0 iis=6
14:23:51 uf4 pc=0 rr=20 di=7 iis=6 rrs=7 los=1 tms=0
14:23:51 uf4 pc=0 rr=20 di=7 iis=6 rrs=7 los=1 tms=0
14:23:59 16 segment ELM { CommD sen
t by DLP in clear Text}
ELM-COMMD SEGMENT TWO SEGMENT 003 SEGMENT FOUR SEGMENT FIVE SEGM
ENT SIX SEGMENT 007 SEGMENT 008 S
EGMENT NINE SEGMENT TEN SEGMENT 0011 SEGMENT 0012 SEGMENT XIII S
EGMENT 0014 SEGMENT 015 SEGMENT 016
14:23:59 uf4 pc=0 rr=28 di=1 iis=6 mbs=0 mes=0 los=1 rss=0 tms=0
14:23:59 uf4 pc=0 rr=28 di=1 iis=6 mbs=0 mes=0 los=1 rss=0 tms=0
14:23:59 uf4 pc=0 rr=28 di=1 iis=6 mbs=0 mes=0 los=1 rss=0 tms=0
14:23:59 uf4 pc=0 rr=26 di=0 iis=6
14:23:59 uf4 pc=0 rr=20 di=7 iis=6 rrs=7 los=1 tms=0
14:23:59 uf4 pc=0 rr=20 di=7 iis=6 rrs=7 los=1 tms=0
14:24: 8 uf4 pc=0 rr=28 di=1 iis=6 mbs=0 mes=3 los=1 rss=3 tms=0
14:24: 8 uf4 pc=0 rr=28 di=1 iis=6 mbs=0 mes=3 los=1 rss=3 tms=0
14:24:16 uf4 pc=0 rr=28 di=1 iis=6 mbs=0 mes=4 los=1 rss=0 tms=0
14:24:16 CommD Closeout rcn=0 uii=6 {
Close-out from radar }
14:24:16 uf4 pc=0 rr=28 di=1 iis=6 mbs=0 mes=4 los=1 rss=0 tms=0
14:24:16 uf4 pc=0 rr=26 di=0 iis=6
14:24:16 uf4 pc=0 rr=20 di=7 iis=6 rrs=7 los=1 tms=0
14:24:16 uf4 pc=0 rr=20 di=7 iis=6 rrs=7 los=1 tms=0

14:58:40 uf4 pc=5 rr=0 di=0 iis=0
14:58:41 uf21 pc0 rr0 di7 iis=0 rrs=0 los=0 tms=1 ma=8822008E79E240
{ CommA linked }
apn=1 gpn=1 cid=1
{ Data Link fields }
14:58:43 uf21 pc0 rr0 di7 iis=0 rrs=0 los=0 tms=2 ma=69E91C49C3C008
14:58:44 uf21 pc0 rr0 di7 iis=0 rrs=0 los=0 tms=6 ma=D9E58000000000
Text=GOOD MORNING AF320
{ Decoded Message }
14:58:45 uf21 pc0 rr0 di7 iis=0 rrs=0 los=0 tms=1 ma=882200A840A90A
apn=1 gpn=1 cid=1
14:58:45 uf21 pc0 rr0 di7 iis=0 rrs=0 los=0 tms=5 ma=00000000000000
Text=THERE
14:58:45 uf21 pc0 rr0 di7 iis=0 rrs=0 los=0 tms=0 ma=88220100336000
apn=1 gpn=1 cid=2
turn to heading ... degrees
14:58:45 uf24 lri=0 crn=1
{ 16 segment CommC from radar }
rc=2 nc=0 mc=82088020869C1EC019E6 rc=1 nc=1 mc=9B6830060A00844984A
8
rc=1 nc=2 mc=CC09AA10C48A609040F0 rc=1 nc=3 mc=222707B00368828C49C
4
rc=1 nc=4 mc=A849E7409AA10C48A608 rc=1 nc=5 mc=F024A707B0024A41A48
0
14:58:45 uf24 lri=0 crn=2
rc=1 nc=6 mc=CA4048829CA12312182A rc=1 nc=7 mc=1279D026A8431229824
0
rc=1 nc=8 mc=F041A707B00679A6DA14 rc=1 nc=9 mc=0182802112612A33026
A
rc=1 nc=10 mc=8431229824104104103C rc=1 nc=11 mc=1089C1EC015A20A31
280
14:58:45 uf24 lri=1 crn=3
rc=1 nc=12 mc=2A1279D026A843122982 rc=1 nc=13 mc=41041041041041041
03C
rc=1 nc=14 mc=1889C1EC01DA20A31271 rc=0 nc=15 mc=2A1279D026A843122
982
ACS = COMM-A CAPABILITY SUBFIELD ADS = A-DEFINITION SUBFIELD AIS
= { decoded in clear text }
AIRCRAFT IDENTIFICATION SUBFIELD BCS = COMM-B CAPABILITY SUBFIELD
14:59: 1 uf4 pc=5 rr=0 di=0 iis=0