

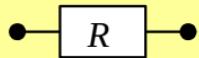
$$u(t) = U \cdot \cos(\omega t + \varphi_U) = \operatorname{Re} [U \cdot e^{j\varphi_U} \cdot e^{j\omega t}] = \operatorname{Re} [\hat{U} \cdot e^{j\omega t}]$$

$$i(t) = I \cdot \cos(\omega t + \varphi_I) = \operatorname{Re} [I \cdot e^{j\varphi_I} \cdot e^{j\omega t}] = \operatorname{Re} [\hat{I} \cdot e^{j\omega t}]$$

Kazalci

$$\hat{U} = U \cdot e^{j\varphi_U}$$

$$\hat{I} = I \cdot e^{j\varphi_I}$$



$$u(t) = R \cdot i(t) = \operatorname{Re} [R \cdot \hat{I} \cdot e^{j\omega t}] \longrightarrow \hat{U} = R \cdot \hat{I}$$



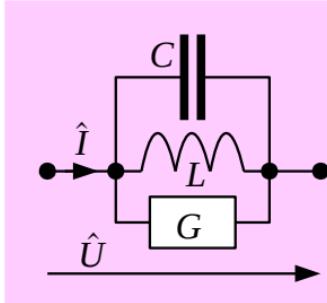
$$u(t) = L \cdot \frac{di(t)}{dt} = \operatorname{Re} [L \cdot \hat{I} \cdot j\omega \cdot e^{j\omega t}] \longrightarrow \hat{U} = j\omega L \cdot \hat{I}$$



$$u(t) = \frac{1}{C} \cdot \int i(t) dt = \operatorname{Re} \left[\frac{1}{C} \cdot \hat{I} \cdot \frac{1}{j\omega} \cdot e^{j\omega t} \right] \longrightarrow \hat{U} = \frac{1}{j\omega C} \cdot \hat{I}$$

$$\begin{array}{c} \bullet \xrightarrow{\hat{I}} \boxed{R} \xrightarrow{\quad} \text{---} \xrightarrow{\quad} \text{---} \\ \hat{U} = \left(R + j\omega L + \frac{1}{j\omega C} \right) \cdot \hat{I} = Z \cdot \hat{I} \end{array}$$

$$Z = R + j\omega L + \frac{1}{j\omega C} = R + jX$$



$$\hat{I} = \left(j\omega C + \frac{1}{j\omega L} + G \right) \cdot \hat{U} = Y \cdot \hat{U}$$

$$G = 1/R$$

$$Y = j\omega C + \frac{1}{j\omega L} + G = G + jB$$